



Biology on the Move

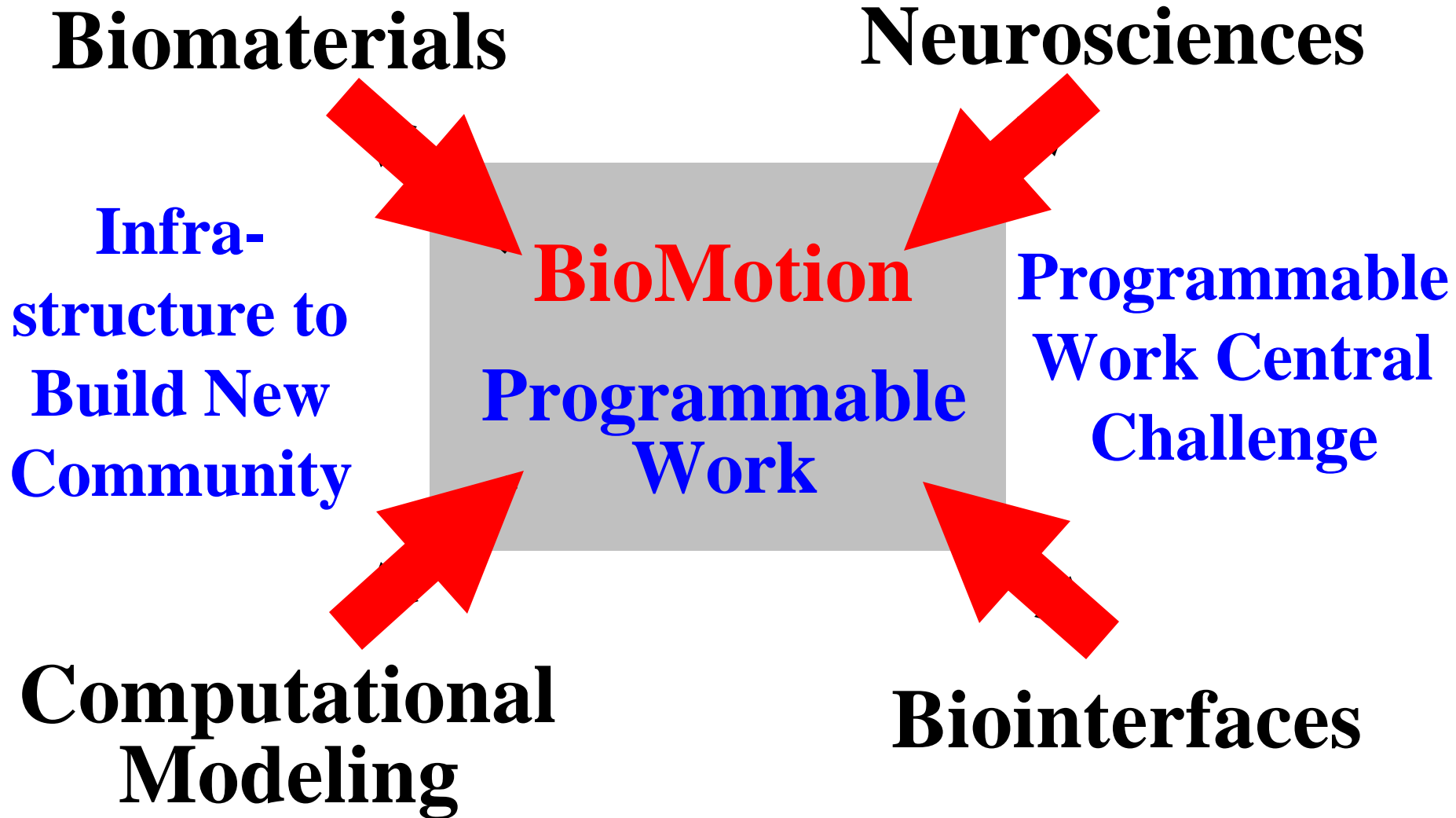
Chairs

Robert Full UC Berkeley

Alan Rudolph DARPA

1. What are critical technical barriers, enablers and opportunities for opening the vista of technological applications?
2. What are the potential technological advancements over the temporal horizon (3-15 years)
3. What are the Defense relevant implications of success?

Age of Integration



BioMotion Vision



- 1. Control and program motion**
- 2. Move in any environment**
- 3. Manipulate any object**

Biomechanical Intersection



Topic: Biology on the Move, From Molecules to Organisms.

Areas of Interest: biolocomotion (walking, running, flying, swimming), group movements (flocks, schools) structural and functional appendages (legs, feet, wings, setae, cilia, flagellae), neuromechanics, integration of mechanics and materials, biological motors, force dynamics (hydrodynamics, aerodynamics)

Actuators and integration

2:30 Montemagno, Carlo D. ATP and nanodevices.
Cornell University

2:50 Daniel, T.L.
University of Washington

3:10 Lieber, R.
University of California, San Diego

Computational neurobiology

3:30 Miller, J.
Montana State University

3:30 – 3:40 BREAK

Flight and neural control

3:40 Dickinson, M.
UC Berkeley

Swimming

4:00 Lauder, G.
Harvard University

Running and flying

4:20 Biewener, A.
Harvard University.

Interface with engineering

4:40 Koditschek, D.
University of Michigan

Focus Open Discussion Alan Rudolph
5:00 Full, R. UC Berkeley

Integration of Molecules to Muscles

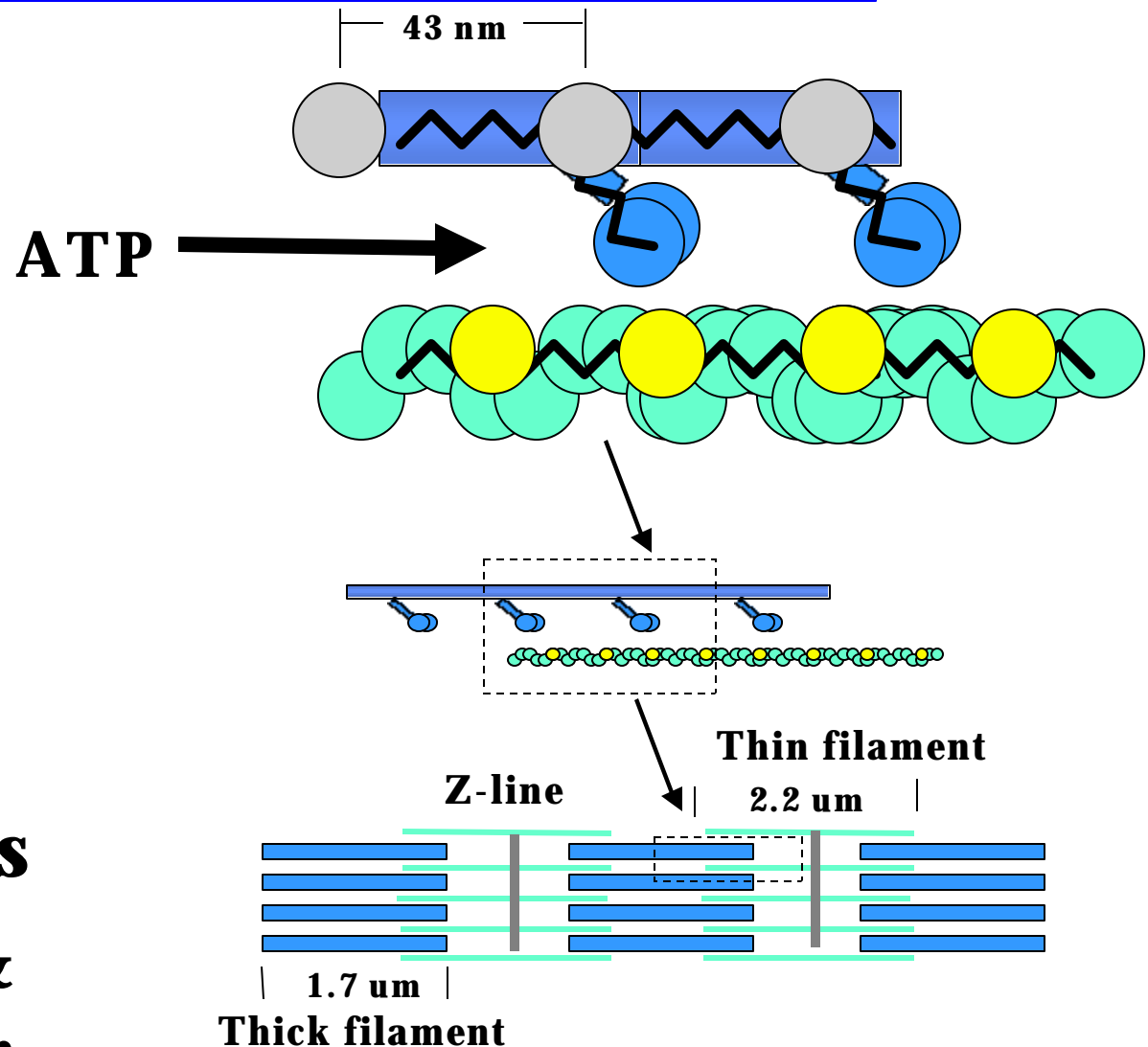


Montemagno
Cornell

**BioEnergy &
Nanodevices**

Daniel
UW

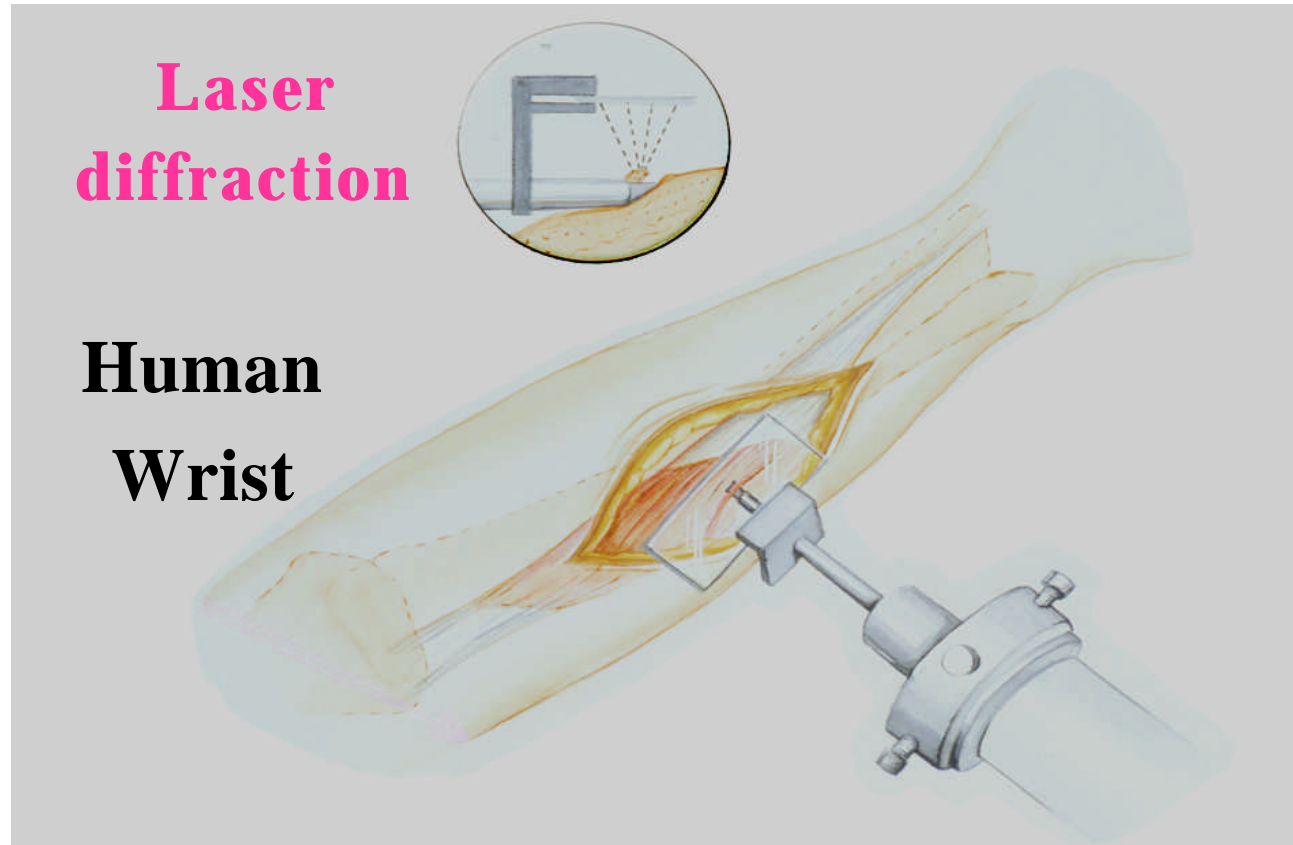
**BioFilaments
Properties &
System Behavior**





Laser diffraction

Tuned mechanical system



Directly Measure Intrinsic Musculoskeletal Properties

Encoding Information & Control



Miller

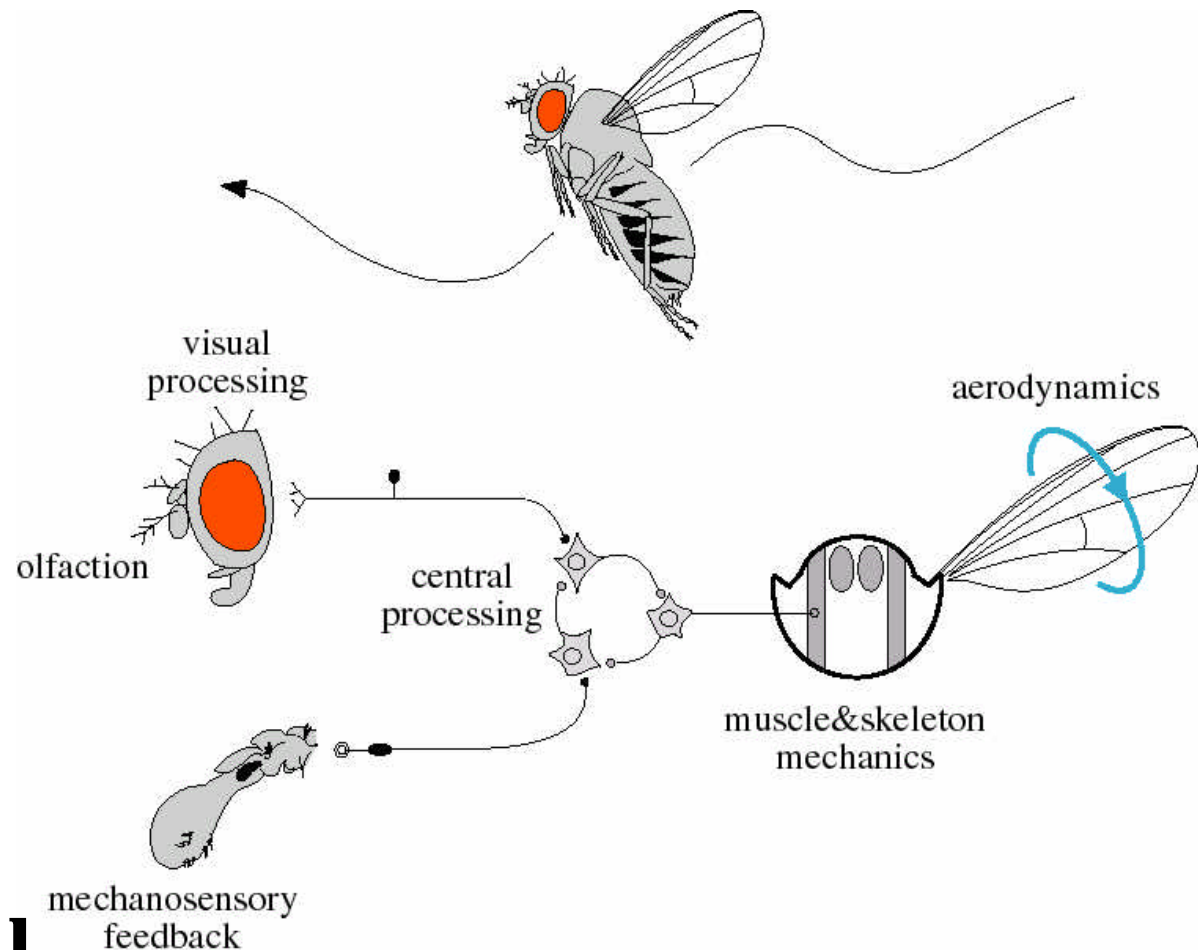
Montana State

**Ensemble
Neural
Encoding**

Dickinson

UC Berkeley

**Neuromechanical
Integration**

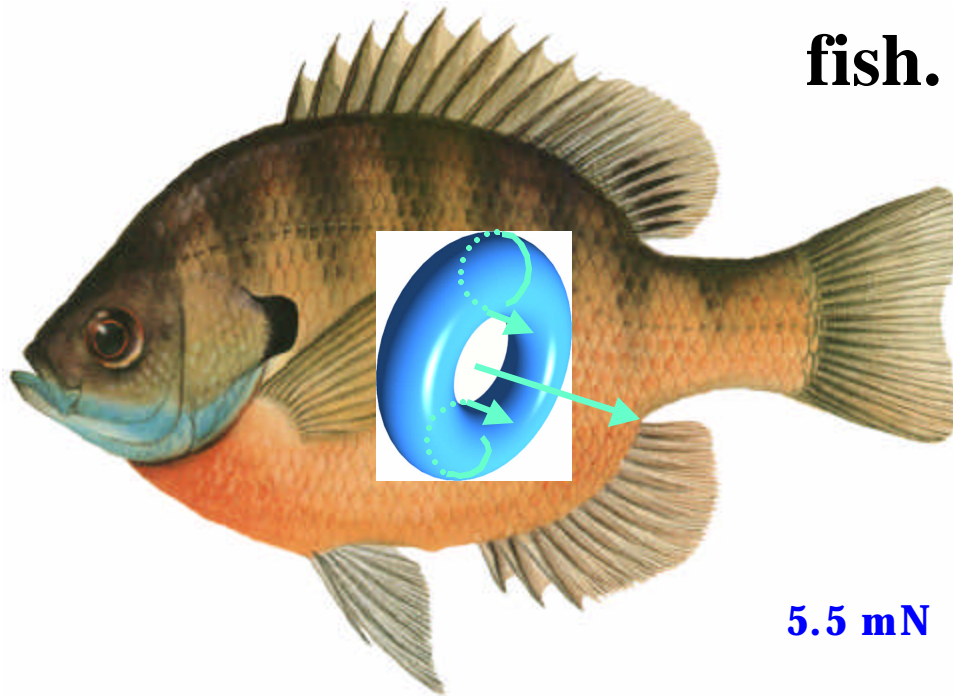


Multimodal Sensory Feedback

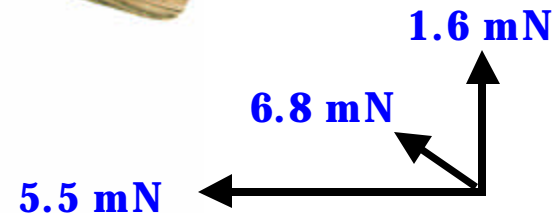
Lauder *Harvard*

Design and Evolution

**Three dimensional
force measurements
in free swimming
fish.**



**Single fin forces
at 0.5 Ls^{-1}**



Integration of Muscles in Free Movement



Biewener *CFS Harvard* Energy Management

Power Output



Avian pectoralis muscle

Force Economy & Elastic Energy Savings



**Kangaroo/wallaby gastrocnemius
& plantaris muscles**

Engineering Perspective



Koditschek
U Michigan

**Biologically Inspired
Dynamic
Robot**

Design

**Energy
Management**

Bandwidth

QuickTime™ and a
decompressor
are needed to see this picture.

“Rhex” **Buehler &
Koditschek**